

## Techno India NJR Institute of Technology

Academic Administration of Techno NJR Institute

Lab Deployment

Name of Faculty: Mr Rajkumar Soni	Subject Code: 7EE4-22	
Subject Name: Advance control system lab	SEM: VII	
Department: Department of Electrical Engineering		
Total No. of Labs Planned: 12		

COURSE OUTCOMES HERE (3 OUTCOMES)

At the end of this course students will be able to:

- 1 Ability to formulate transfer function for given control system problems.
- 2 Ability to find time response of given control system model.
- 3 Plot Root Locus and Bode plots for given control system model
- 4 Ability to design Lead, Lag, Lead-Lag systems in control systems
- 5 Ability to design PID controllers for given control system model

Labs	Name of Experiment
No.	
1	Determination of transfer functions of DC servomotor and
	AC servomotor.
2	Time domain response of rotary servo and Linear servo (first
	order and second order) systems using MATLAB/Simulink.
3	Simulate Speed and position we fit of DC Motor
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(Principal)

4	Frequency response of small-motion, linearized model of
	industrial robot (first and second order) system using
	MATLAB.
5	Characteristics of PID controllers using MATLAB. Design
	and implementation of P, PI and PID Controllers for
	temperature and level control systems;
6	Design and implement closed loop control of DC Motor
	using MATLAB/Simulink and suitable hardware platform.
7	Implementation of digital controller using microcontroller;
8	Design and implementation of controller for practical
	systems - inverted pendulum system.
9	To design and implement control action for maintaining a
	pendulum in the upright position (even when subjected to
	external disturbances) through LQR technique in an
	Arduino Mega.
10	The fourth order, nonlinear and unstable real-time control
	system (Pendulum & Cart Control System)
11	Mini project on real life motion control system

## **TEXT/REFERENCE BOOKS**

- 1. Smarjit Ghosh, Control Systems: Theory and Applications, 2/e, Pearson Publisher. 2004
- 2 Dhannesh N. Manik: Control System, Cengage Learning. 2012
- 3 I. J. Nagrath and M. Gopal: Control Systems Engineering, 3rd Ed, New Age Publication.
- 4 K. R. Varmah: Control Systems, MGH 2010
- 5 Anandnatrajan et. al.: Control System Risigneering, 4th ed., Scitech Pub.

Uch J UT SATURA Dr. Pankaj Kumar Porwa (Principal)